# $\S3.6$ Permutation Groups

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#### MATH 546/701I

#### University of South Carolina

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In fact, this natural way will be important in the proof of Cayley's theorem.

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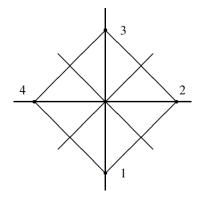
a change in position where the distance between points is preserved and figures remain congruent (having the same size and shape). It may be

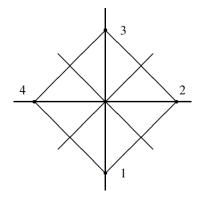
- a translation (slide)
- a reflection (flip)
- a rotation (turn)
- or a combination of these.

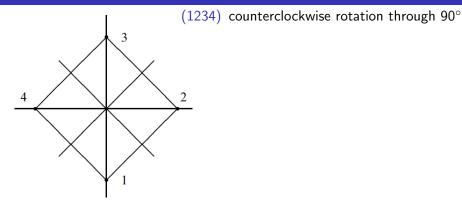
Each of the rigid motions determines a permutation of the vertices of the square, and the permutation notation gives a convenient way to describe these motions.

There are a total of **eight** rigid motions of a square. (Why?)

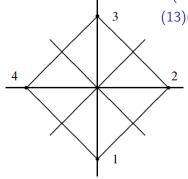
- There are four choices of a position in which to place first vertex A,
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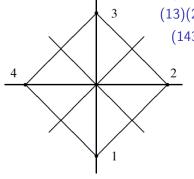




(1234) counterclockwise rotation through 90°(13)(24) counterclockwise rotation through 180°



(1234) counterclockwise rotation through 90°
(13)(24) counterclockwise rotation through 180°
(1432) counterclockwise rotation through 270°



2

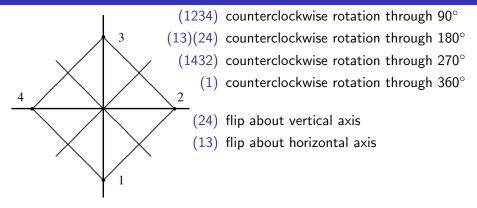
3

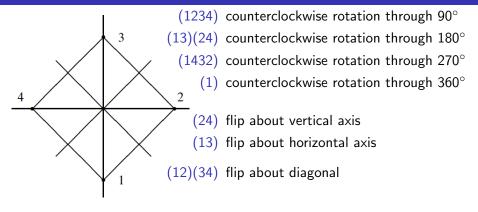
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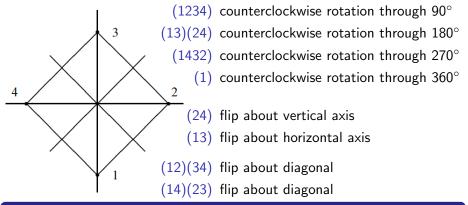
4

(1234) counterclockwise rotation through 90° (13)(24) counterclockwise rotation through 180° (1432) counterclockwise rotation through 270° (1) counterclockwise rotation through 360° 2 (24) flip about vertical axis

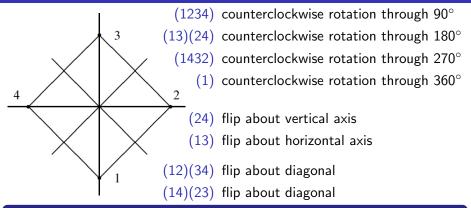
4





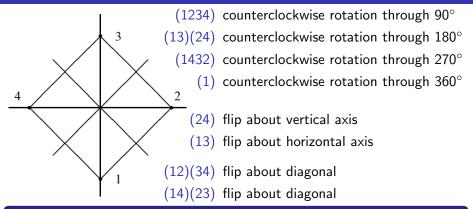


Note 2



#### Note 2

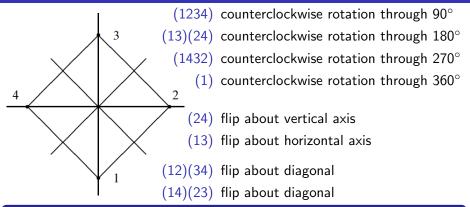
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#### Question 1

What is the order of each rigid motion?

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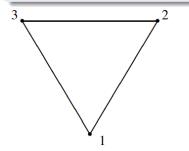
### Rigid motions of a square: Multiplication table

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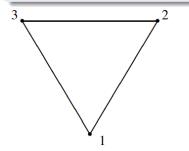
	(1)	(1234)	(13)(24)	(1432)	(24)	(12)(34)	(13)	(14)(23)
(1)	(1)	(1234)	(13)(24)	(1432)	(24)	(12)(34)	(13)	(14)(23)
(1234)	(1234)	(13)(24)	(1432)	(1)	(12)(34)	(13)	(14)(23)	(24)
(13)(24)	(13)(24)	(1432)	(1)	(1234)	(13)	(14)(23)	(24)	(12)(34)
(1432)	(1432)	(1)	(1234)	(13)(24)	(14)(23)	(24)	(12)(34)	(13)
(24)	(24)	(14)(23)	(13)	(12)(34)	(1)	(1432)	(13)(24)	(1234)
(12)(34)	(12)(34)	(24)	(14)(23)	(13)	(1234)	(1)	(1432)	(13)(24)
(13)	(13)	(12)(34)	(24)	(14)(23)	(13)(24)	(1234)	(1)	(1432)
(14)(23)	(14)(23)	(13)	(12)(34)	(24)	(1432)	(13)(24)	(1234)	(1)

Proposition 1

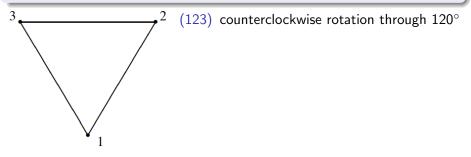
#### Proposition 1



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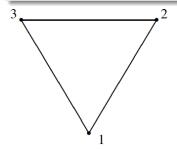


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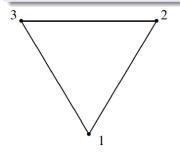
The rigid motions of an equilateral triangle yield the group  $S_3$ .



(123) counterclockwise rotation through 120°(132) counterclockwise rotation through 240°

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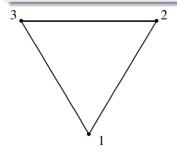


(123) counterclockwise rotation through  $120^{\circ}$  (132) counterclockwise rotation through  $240^{\circ}$ 

(1) counterclockwise rotation through  $360^{\circ}$ 

#### Proposition 1

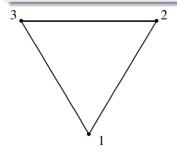
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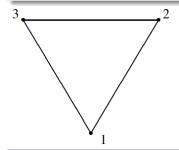
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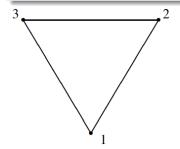


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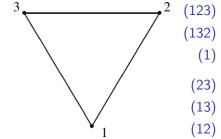
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Note 4 (Another notion for describing Rigid Motions of a Square)

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- (12) flip about angle bisector

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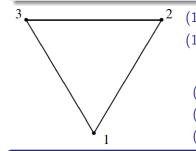
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Proposition 2

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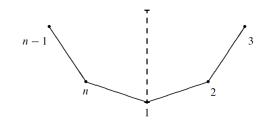
There are 2n rigid motions of a regular n-gon.

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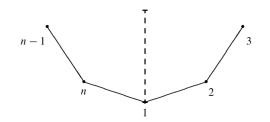


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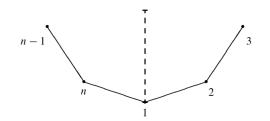


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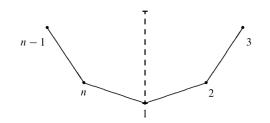


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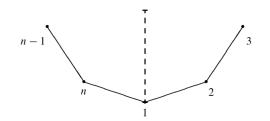


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Yi

Consider the set  $S = \{a^k, a^k b \mid 0 \le k < n\}$  of rigid motions.

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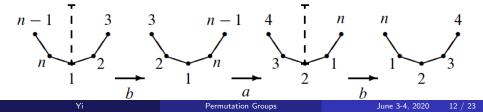
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Proposition 3 (Note 5)

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- The dihedral group  $D_n$  is one important example of subgroups of  $S_n$ .

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$$D_n = \{a^k, a^k b \mid 0 \le k < n\}, \text{ where } a^n = e, b^2 = e, ba = a^{-1}b.$$

- We will not list all the subgroups of  $S_n$ . (Why?) [there are too many!!]
- The "simple" subgroups of  $S_n$ : cyclic subgroup generated by  $\sigma \in S_n$ .
- The dihedral group  $D_n$  is one important example of subgroups of  $S_n$ .
- The alternating group  $A_n$  is another one important example. (soon!)

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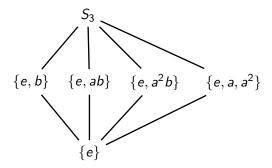
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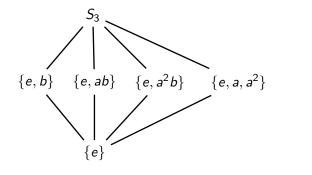
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Note that  $D_3 = S_3 = \{e, a, a^2, b, ab, a^2b\}$ , where  $a^3 = e, b^2 = e, ba = a^2b$ . Yi Permutation Groups June 34, 2020 14/23

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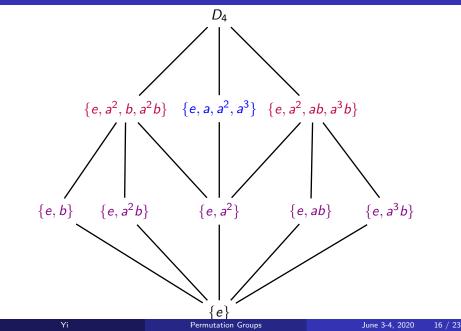
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### Subgroups of D<sub>4</sub> cont.: Subgroup diagram

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III. Therefore, 
$$|A_n| = |O_n| = \frac{|S_n|}{2} = \frac{n!}{2}$$
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Permutation Groups

(12)(34), (13)(24), (14)(23)

June 3-4, 2020

20 / 23

#### Upshot:

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